

CURRICULUM VITAE

Name: Sergey Anatolievich Lobov
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Date and Place of Birth: 19 November 1974, Nizhny Novgorod, USSR



Areas of Specializations: biophysics, bioelectrogenesis, spiking neuronal networks, information processing in biology, models of synaptic plasticity and learning.

Education

2003 Ph.D. in biology, Nizhny Novgorod State University
1998 Graduated from Nizhny Novgorod State University, Biological Faculty

Additional Education

2008-2009 Programmer's course at NIIT. I, II stage (C/C++/Unix/English)
2004 English courses «Denis School»

Research Experience

2009-present Computer modeling of spiking neural networks. Implementation of complex computer program "NeuroNet" which include several models of spiking neurons, delays, synaptic plasticity and growing processes. Neuronal learning simulation and its demonstration in neuroanimates – robots controlled by neurons.
1997-2003 Studies of bioelectric reactions (BER) in plants (Nizhny Novgorod State University, Biophysics Department). Using macroelectrode technique, designing software for BER registration, computer modeling some electrophysiology processes, studying the electrophysiological stage in perception, using luciferin-luciferase method for ATP measuring, dose injure by cold and hit.
1995, 1996 Studies of synaptic plasticity and epileptic activity in rat hippocampus (2-month student research works at Institute of Theoretical and Experimental Biophysics, Puschino, Russia). Using microelectrode (extracellulars) technique, making microelectrodes, making living slices of rat hippocampus.

Employment

2020-present Researcher, Neuroscience and Cognitive Technology Laboratory, Center for Technologies in Robotics and Mechatronics Components, Innopolis University, Innopolis.
2012-present Researcher, Lobachevsky State University of Nizhni Novgorod
2001-2015 System administrator, the trade company Kontinent ETS (Uzola), Nizhny Novgorod
2011-2012 Researcher, Laboratory of Nonlinear Processes in Living Systems, Institute of Applied Physics of RAS (part time)
2009 Software designer, Mera-NN
1999-2001 System administrator, the geology company CGGE, Nizhny Novgorod
1997-1999 Engineer, The IT company VMNUC VTI (part time)
1997 Software designer (modeling in MATLAB), The Geology firm Geocos (part time).

Main publications

1. Lobov, S.A.; Zharinov, A.I.; Makarov, V.A.; Kazantsev, V.B. Spatial Memory in a Spiking Neural Network with Robot Embodiment. *Sensors* 2021, 21(8), 2678.
2. Villacorta-Atienza, J.A.; Calvo Tapia, C.; Díez-Hermano, S.; Sánchez-Jiménez, A.; Lobov, S.; Krilova, N.; Murciano, A.; López-Tolsa, G.E.; Pellón, R.; Makarov, V.A. Static internal representation of dynamic situations reveals time compaction in human cognition. *J. Adv. Res.* 2021, 28, 111–125.
3. Lobov, S.A.; Mikhaylov, A.N.; Shamshin, M.; Makarov, V.A.; Kazantsev, V.B. Spatial properties of STDP in a self-learning spiking neural network enable controlling a mobile robot. *Front. Neurosci.* 2020, 14, 88.

4. Lobov, S.A.; Chernyshov, A. V; Krilova, N.P.; Shamshin, M.O.; Kazantsev, V.B. Competitive Learning in a Spiking Neural Network: Towards an Intelligent Pattern Classifier. *Sensors* 2020, 20.
5. Mikhaylov, A.; Pimashkin, A.; Pigareva, Y.; Gerasimova, S.A.; Lobov, S.; Gryaznov, E.; Talanov, M.; Lavrov, I.; Demin, V.; Erokhin, V.; et al. Neurohybrid Memristive CMOS-Integrated Systems for Biosensors and Neuroprosthetics. *Front. Neurosci.* 2020, 14, 358.
6. Gordleeva, S.Y.; Lobov, S.A.; Grigorev, N.A.; Savosenkov, A.O.; Shamshin, M.O.; Lukoyanov, M. V; Khoruzhko, M.A.; Kazantsev, V.B. Real-Time EEG–EMG Human–Machine Interface-Based Control System for a Lower-Limb Exoskeleton. *IEEE Access* 2020, 8, 84070–84081.
7. Villacorta-Atienza, J.A.; Calvo Tapia, C.; Díez-Hermano, S.; Khoruzhko, M.; Lobov, S.; Potapov, I.; Sánchez-Jiménez, A.; Makarov, V.A. Semantic Knowledge Representation for Strategic Interactions in Dynamic Situations. *Front. Neurorobot.* 2020.
8. Bazhanova, M. V; Krylova, N.P.; Kazantsev, V.B.; Khramov, A.E.; Lobov, S.A. Synchronization in a Network of Spiking Neural Oscillators with Plastic Connectivity. *Radiophys. Quantum Electron.* 2020, 63, 298–309.
9. Lobov, S. A. Generalized Memory of STDP-Driven Spiking Neural Network. *Math. Biol. Bioinf.* 2019, 14(2), 649–664.
10. Lobov, S.; Krilova, N.; Kastalskiy, I.; Kazantsev, V.; Makarov, V.A. Latent Factors Limiting the Performance of sEMG-Interfaces. *Sensors* 2018, 18, 1122.
11. Mironov, V.I.; Lobov, S.A.; Krylova, N.P.; Gordleeva, S.Y.; Kaplan, A.Y.; Buylova, T.V.; Bakhshiyyev, A.V.; Shchurovsky, D.V.; Wagner, V.O.; Kastalskiy, I.A.; et al. Development of a Neurally-Controlled Vehicle — Neuro-Mobile — for Driving by Individuals with Motor Deficiency. *Sovrem. Tehnol. v Med.* 2018, 10, 49.
12. Mikhaylov, A.N.; Morozov, O.A.; Ovchinnikov, P.E.; Antonov, I.N.; Belov, A.I.; Korolev, D.S.; Sharapov, A.N.; Gryaznov, E.G.; Gorshkov, O.N.; Pigareva, Y.I.; et al. One-Board Design and Simulation of Double-Layer Perceptron Based on Metal-Oxide Memristive Nanostructures. *IEEE Trans. Emerg. Top. Comput. Intell.* 2018, 2, 371–379.
13. Villacorta-Atienza, J.A.; Calvo, C.; Lobov, S.; Makarov, V.A. Limb Movement in Dynamic Situations Based on Generalized Cognitive Maps. *Math. Model. Nat. Phenom.* 2017, 12, 15–29.
14. Lobov, S.A.; Zhuravlev, M.O.; Makarov, V.A.; Kazantsev, V.B. Noise Enhanced Signaling in STDP Driven Spiking-Neuron Network. *Math. Model. Nat. Phenom.* 2017, 12, 109–124.
15. Lobov, S.; Simonov, A.; Kastalskiy, I.; Kazantsev, V. Network response synchronization enhanced by synaptic plasticity. *Eur. Phys. J. Spec. Top.* 2016, 225, 29–39.
16. Lobov, S.; Kazantsev, V.; Makarov, V.A. Spiking neurons as universal building blocks for hybrid systems. *Adv. Sci. Lett.* 2016, 22, 2633–2637.
17. Lobov, S.A.; Mironov, V.I.; Kastalskiy, I.A.; Kazantsev, V.B. Combined Use of Command-Proportional Control of External Robotic Devices Based on Electromyography Signals. *Sovrem. Tehnol. v Med.* 2015, 7, 30–38.
18. Lobov, S.; Mironov, V.; Kastalskiy, I.; Kazantsev, V. A Spiking Neural Network in sEMG Feature Extraction. *Sensors* 2015, 15, 27894–27904.